

Expressions in Cylindrical Coordinates

Velocity: $\mathbf{V} = V_r \mathbf{e}_r + V_\theta \mathbf{e}_\theta + V_z \mathbf{k}$

Gravity: $\mathbf{g} = g_r \mathbf{e}_r + g_\theta \mathbf{e}_\theta + g_z \mathbf{k}$

Differential Operator: $\nabla = \frac{\partial}{\partial r} \mathbf{e}_r + \frac{1}{r} \frac{\partial}{\partial \theta} \mathbf{e}_\theta + \frac{\partial}{\partial z} \mathbf{k}$ **Gradient:** $\nabla p = \frac{\partial p}{\partial r} \mathbf{e}_r + \frac{1}{r} \frac{\partial p}{\partial \theta} \mathbf{e}_\theta + \frac{\partial p}{\partial z} \mathbf{k}$

Laplacian of a Vector: $\nabla^2 \mathbf{V} = \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\partial^2}{\partial z^2} \right) (V_r \mathbf{e}_r + V_\theta \mathbf{e}_\theta + V_z \mathbf{k})$

Divergence: $\nabla \cdot \mathbf{V} = \frac{1}{r} \frac{\partial}{\partial r} (r V_r) + \frac{1}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{\partial V_z}{\partial z} \equiv \frac{\partial V_r}{\partial r} + \frac{V_r}{r} + \frac{1}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{\partial V_z}{\partial z}$

Curl: $\nabla \times \mathbf{V} = \left(\frac{1}{r} \frac{\partial V_z}{\partial \theta} - \frac{\partial V_\theta}{\partial z} \right) \mathbf{e}_r + \left(\frac{\partial V_r}{\partial z} - \frac{\partial V_z}{\partial r} \right) \mathbf{e}_\theta + \frac{1}{r} \left[\frac{\partial}{\partial r} (r V_\theta) - \frac{\partial V_r}{\partial \theta} \right] \mathbf{k}$

Continuity: $\nabla \cdot \mathbf{V} = \frac{1}{r} \frac{\partial}{\partial r} (r V_r) + \frac{1}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{\partial V_z}{\partial z} \equiv \frac{\partial V_r}{\partial r} + \frac{V_r}{r} + \frac{1}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{\partial V_z}{\partial z} = 0$

Incompressible NS: $\frac{\partial \mathbf{V}}{\partial t} + (\mathbf{V} \cdot \nabla) \mathbf{V} \equiv \frac{\partial \mathbf{V}}{\partial t} + \nabla \left(\frac{\mathbf{V}^2}{2} \right) - \mathbf{V} \times (\nabla \times \mathbf{V}) = -\frac{\nabla p}{\rho} + \mathbf{g} + \nu \nabla^2 \mathbf{V}$

Using Vector Identity: $(\mathbf{V} \cdot \nabla) \mathbf{V} = \frac{1}{2} \nabla (\mathbf{V} \cdot \mathbf{V}) - \mathbf{V} \times (\nabla \times \mathbf{V})$ and $\nu = \frac{\mu}{\rho}$

NS r -momentum: $\rho \left(\frac{D V_r}{D t} - \frac{V_\theta^2}{r} \right) = -\frac{\partial p}{\partial r} + \mu \left(\nabla^2 V_r - \frac{V_r}{r^2} - \frac{2}{r^2} \frac{\partial V_\theta}{\partial \theta} \right) + \rho g_r$

NS θ -momentum: $\rho \left(\frac{D V_\theta}{D t} + \frac{V_r V_\theta}{r} \right) = -\frac{1}{r} \frac{\partial p}{\partial \theta} + \mu \left(\nabla^2 V_\theta - \frac{V_\theta}{r^2} + \frac{2}{r^2} \frac{\partial V_r}{\partial \theta} \right) + \rho g_\theta$

NS z -momentum: $\rho \frac{D V_z}{D t} = -\frac{\partial p}{\partial z} + \mu \nabla^2 V_z + \rho g_z$

Substantial Derivative: $\frac{D A}{D t} = \frac{\partial A}{\partial t} + V_r \frac{\partial A}{\partial r} + \frac{V_\theta}{r} \frac{\partial A}{\partial \theta} + V_z \frac{\partial A}{\partial z}$

Laplacian: $\nabla^2 = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\partial^2}{\partial z^2} \equiv \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\partial^2}{\partial z^2}$

Stream Function Definition: $V_r = \frac{1}{r} \frac{\partial \psi}{\partial \theta}$ $V_\theta = -\frac{\partial \psi}{\partial r}$ (in 2-D only)

Stream Function Equation: $\nabla^2 \psi = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \psi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \psi}{\partial \theta^2} = 0$ from $\nabla \times \mathbf{V} = 0$

Potential Function Definition: $V_r = -\frac{\partial \phi}{\partial r}$ $V_\theta = -\frac{1}{r} \frac{\partial \phi}{\partial \theta}$ $V_z = -\frac{\partial \phi}{\partial z}$ from $\mathbf{V} = -\nabla \phi$

Potential Function Equation: $\nabla^2 \phi = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} + \frac{\partial^2 \phi}{\partial z^2} = 0$ from $\nabla \cdot \mathbf{V} = 0$

Viscous Shear Stresses: $\tau_{rr} = 2\mu \frac{\partial V_r}{\partial r}$ $\tau_{\theta\theta} = 2\mu \left(\frac{1}{r} \frac{\partial V_\theta}{\partial \theta} + \frac{V_r}{r} \right)$ $\tau_{zz} = 2\mu \frac{\partial V_z}{\partial z}$

Off-Diagonal: $\tau_{r\theta} = \mu \left[\frac{1}{r} \frac{\partial V_r}{\partial \theta} + r \frac{\partial}{\partial r} \left(\frac{V_\theta}{r} \right) \right]$ $\tau_{\theta z} = \mu \left(\frac{1}{r} \frac{\partial V_z}{\partial \theta} + \frac{\partial V_\theta}{\partial z} \right)$ $\tau_{zr} = \mu \left(\frac{\partial V_z}{\partial r} + \frac{\partial V_r}{\partial z} \right)$